

# *A posteriori* soundness for nondeterministic abstract interpretations

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# Questions you don't want at your defense

- “But, why did you prove it ***that*** way?”
- “But, why is that ***necessary***?”
- “So, why ***did*** the Cousots do it that way?”

# Nondeterministic Abstract Interpretation

- Where did it come from?
- How do you prove it sound?
- Why would you want to use it?

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- Where did it come from?
  - Frustration with the standard recipe.
- How do you prove it sound?
  - *A posteriori* proof technique.
- Why would you want to use it?
  - Better speed, better precision.

# Outline

- Review standard recipe.
- Find annoyances.
- Get rid of them.

# The Standard Recipe

Define concrete state-space:  $L$

Define concrete semantics:  $f : L \rightarrow L$

Define abstract state-space:  $\hat{L}$

Define abstraction map:  $\alpha : L \rightarrow \hat{L}$

Define abstract semantics:  $\hat{f} : \hat{L} \rightarrow \hat{L}$

Prove  $\hat{f}$  simulates  $f$  under  $\alpha$ .

# The *A Posteriori* Recipe

Define concrete state-space:  $L$

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Define abstract state-space:  $\hat{L}$

Define abstract semantics:  $\hat{f} : \hat{L} \rightarrow \hat{L}$

Execute abstract semantics to obtain  $\hat{\ell}' = \hat{f}(\hat{\ell})$ .

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Define concrete state-space:  $L$

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Define abstract state-space:  $\hat{L}$

Define abstract semantics:  $\hat{f} : \hat{L} \rightarrow 2^{\hat{L}}$

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# Illustrating the Standard Recipe

# Malloc: The Language

$v := \text{malloc}()$



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*lab* :  $v := \text{malloc}()$

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$$f(\llbracket v := \text{malloc}() \rrbracket : \vec{i}, \sigma) = (\vec{i}, \sigma[v \mapsto a'])$$



Fresh

# Concrete Semantics

$$State = Instruction \times Store$$



Fresh

$$f(\llbracket v := \text{malloc}() \rrbracket : \vec{i}, \sigma) = (\vec{i}, \sigma[v \mapsto a'])$$

$$a' = \text{alloc}(\varsigma)$$

# Concrete Semantics

$$State = Instruction \times Store$$



Fresh

$$f(\llbracket v := \text{malloc}() \rrbracket : \vec{i}, \sigma) = (\vec{i}, \sigma[v \mapsto a'])$$

$$a' = \text{alloc}(\varsigma) = \max(\text{range}(\sigma)) + 1$$

# Abstract Semantics

$$\widehat{State} = Instruction \times \widehat{Store}$$

$$\hat{f}(\llbracket v := \text{malloc}() \rrbracket : \vec{i}, \hat{\sigma}) = (\vec{i}, \hat{\sigma}[v \mapsto \hat{a}])$$

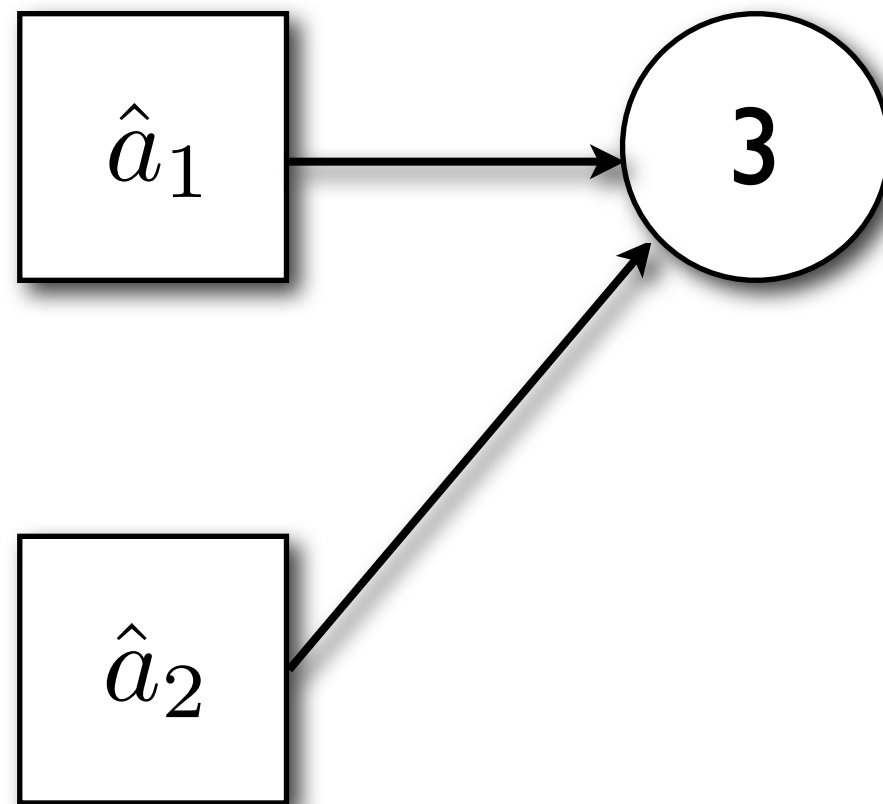
$$\hat{a} = \widehat{\text{alloc}}(\hat{\varsigma}) \quad (\text{from some finite set})$$

# What to allocate?

- Abstract addresses = Scarce resource
- Avoid over-allocation: Good for speed
- Avoid under-allocation: Good for precision



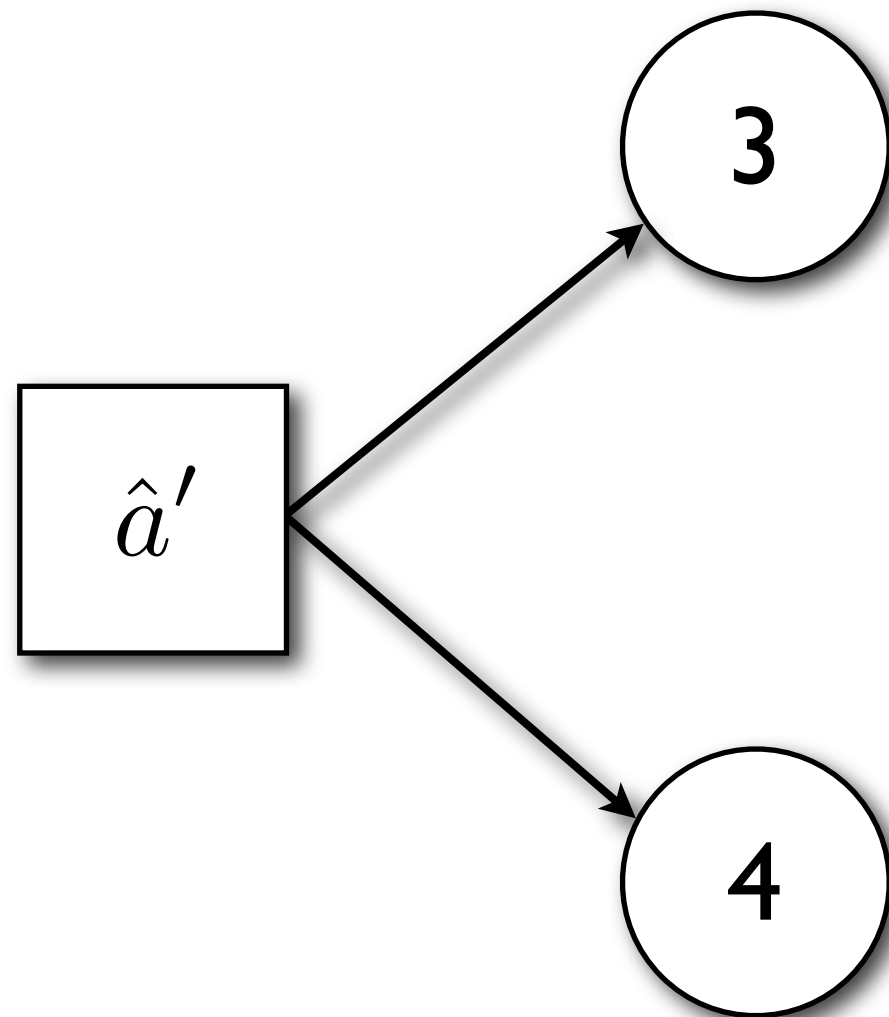
# Example: Over-allocation



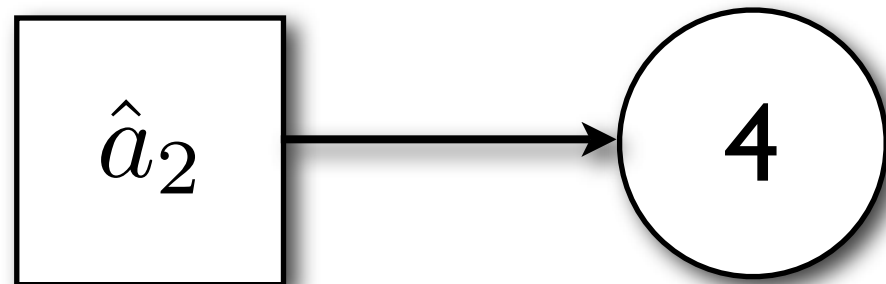
# Example: Over-allocation



# Example: Under-allocation



# Example: Under-allocation



# Allocation heuristics

Observation: Objects from like contexts act alike.

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Example:  $\widehat{\text{alloc}}(\llbracket lab : \dots \rrbracket : \vec{i}, -) = lab$

# Annoyance: Soundness

If

$$\alpha(\varsigma) \sqsubseteq \hat{\varsigma}$$

then

$$\alpha(f(\varsigma)) \sqsubseteq \hat{f}(\hat{\varsigma})$$

# Annoyance: Soundness

If

$$\alpha(\varsigma) \sqsubseteq \hat{\varsigma}$$

then

$$\alpha_{Addr}(\text{alloc}(\varsigma)) \sqsubseteq \widehat{\text{alloc}}(\hat{\varsigma})$$



# The Issue

$$\text{alloc}(-, \sigma) = \max(\text{range}(\sigma)) + 1$$

$$\widehat{\text{alloc}}(\llbracket lab : \dots \rrbracket : \vec{i}, -) = lab$$

What abstraction map will work here?

# Example

A :  $x := \text{malloc}()$

B :  $y := \text{malloc}()$

$\sigma = [x \rightarrow 1, y \rightarrow 2]$

$\alpha_{Addr} = [1 \rightarrow A, 2 \rightarrow B]$

# Example

B :  $y := \text{malloc}()$

A :  $x := \text{malloc}()$

$\sigma = [x \rightarrow 1, y \rightarrow 2]$

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# Example

B :  $y := \text{malloc}()$

A :  $x := \text{malloc}()$

$\sigma = [x \rightarrow 2, y \rightarrow 1]$

$\alpha_{Addr} = [1 \rightarrow A, 2 \rightarrow B]$

# Example

B :  $y := \text{malloc}()$

A :  $x := \text{malloc}()$

$\sigma = [x \rightarrow 2, y \rightarrow 1]$

$\alpha_{Addr} = [2 \rightarrow A, 1 \rightarrow B]$

# Standard Solution

Change the concrete semantics!

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$$Addr = \mathbb{N}$$

$$\text{alloc}(\_, \sigma) = \max(\text{range}(\sigma)) + 1$$

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$$Addr = \mathbb{N} \times Lab$$

$$\text{alloc}(\llbracket lab : \dots \rrbracket, \sigma) = (\max(\text{range}(\sigma)_1) + 1, lab)$$



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Change the concrete semantics!

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$$\text{alloc}(\llbracket lab : \dots \rrbracket, \sigma) = (\max(\text{range}(\sigma)_1) + 1, lab)$$

$$\alpha(-, lab) = lab$$

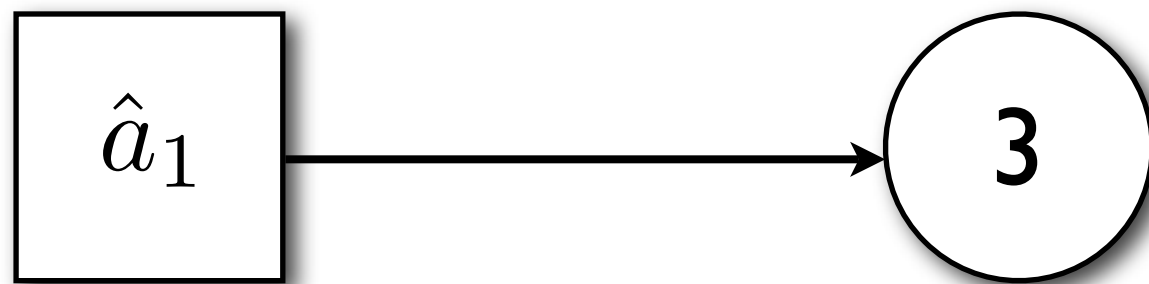
**Another problem:  
Heuristics sometimes  
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Why not adapt on the fly?

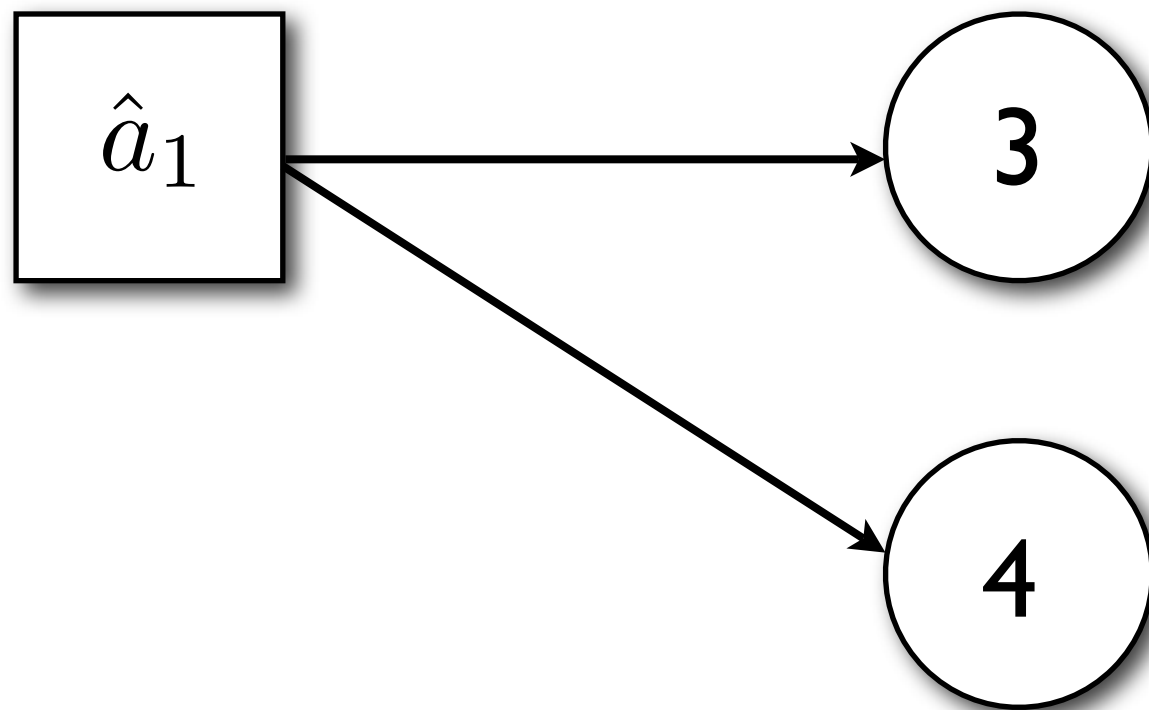
# Example: Greedy Strategy

Heuristic says, “Allocate  $\hat{a}_1$ , and bind 4.”



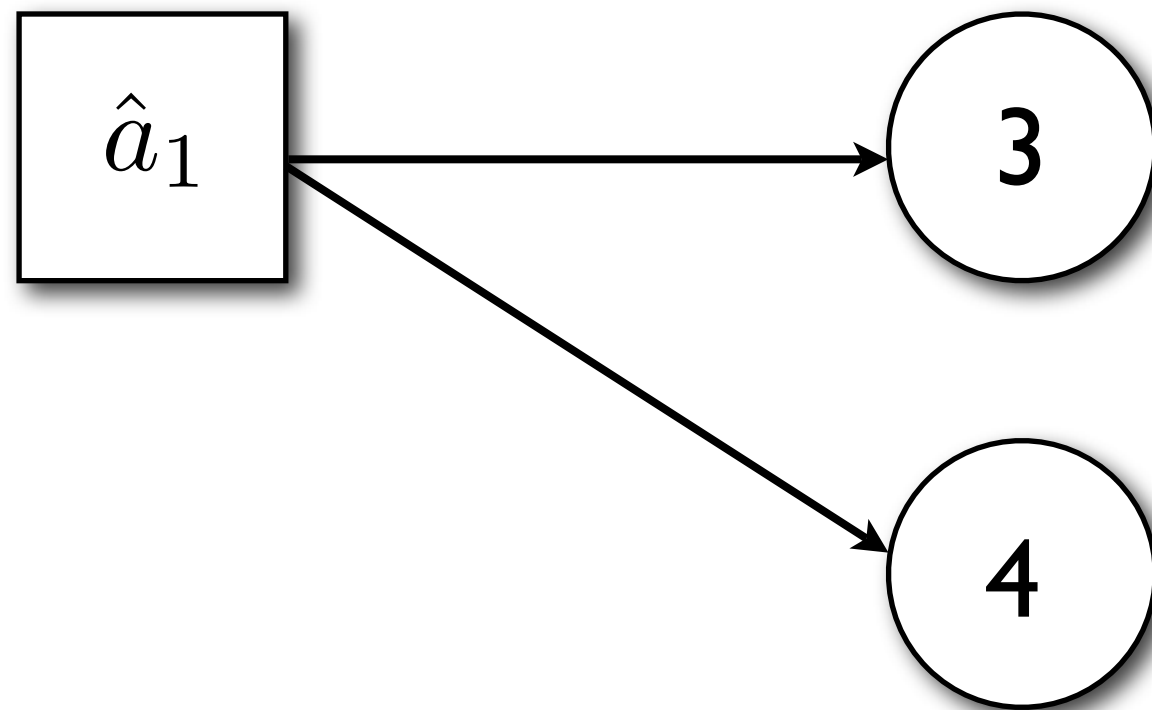
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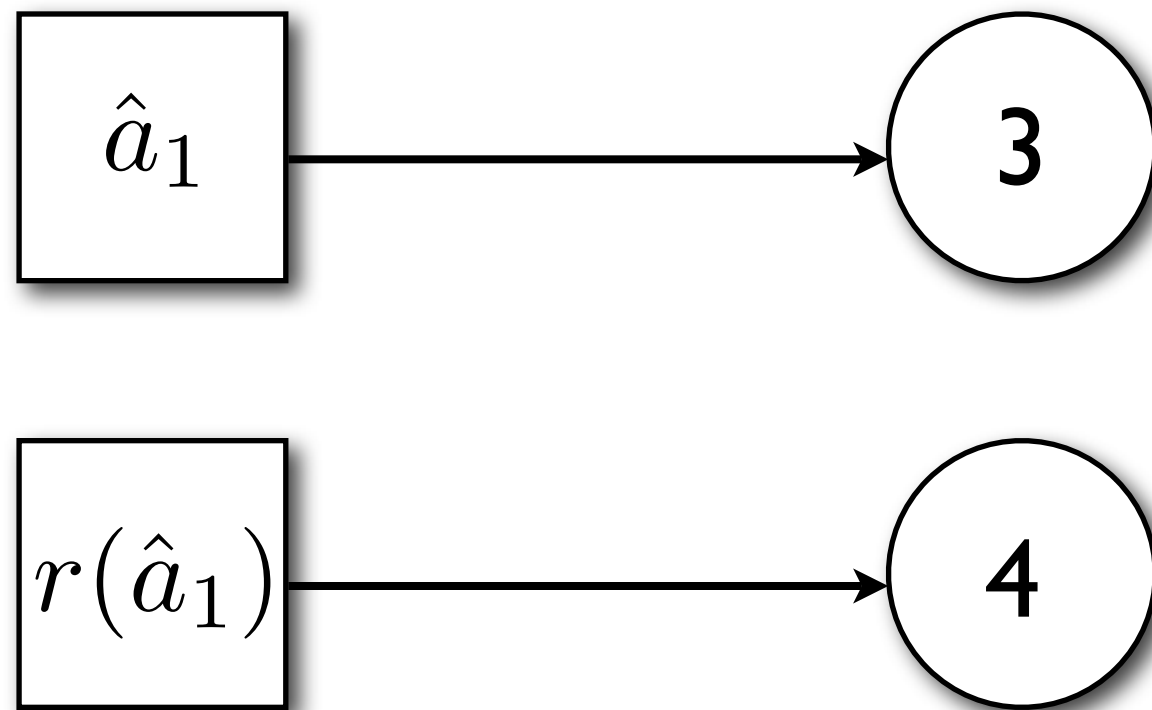
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Adaptive allocator says, “Try  $r(\hat{a}_1)$  first.”

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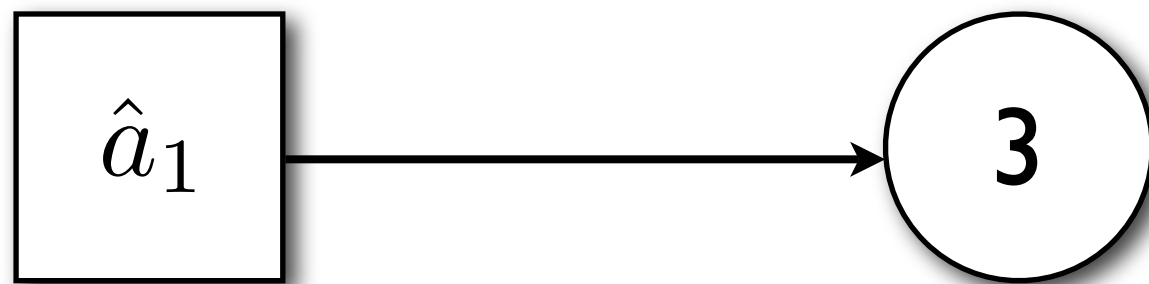
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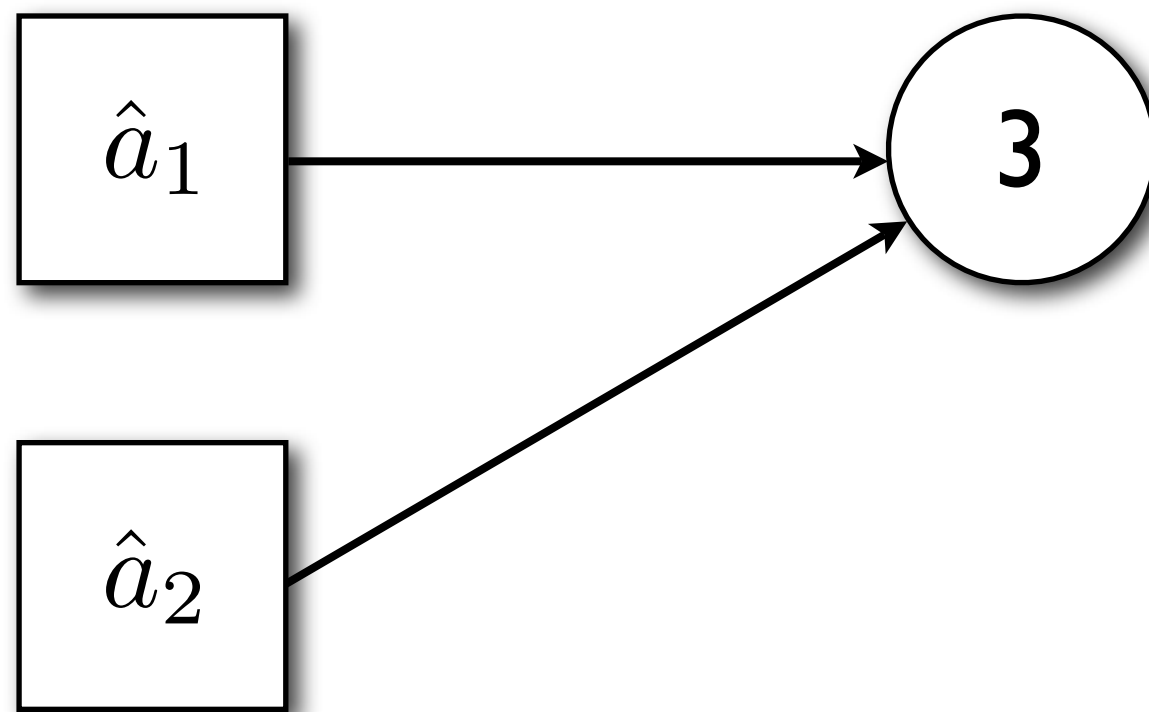
Heuristic says, “Allocate  $\hat{a}_2$ , and bind 3.”





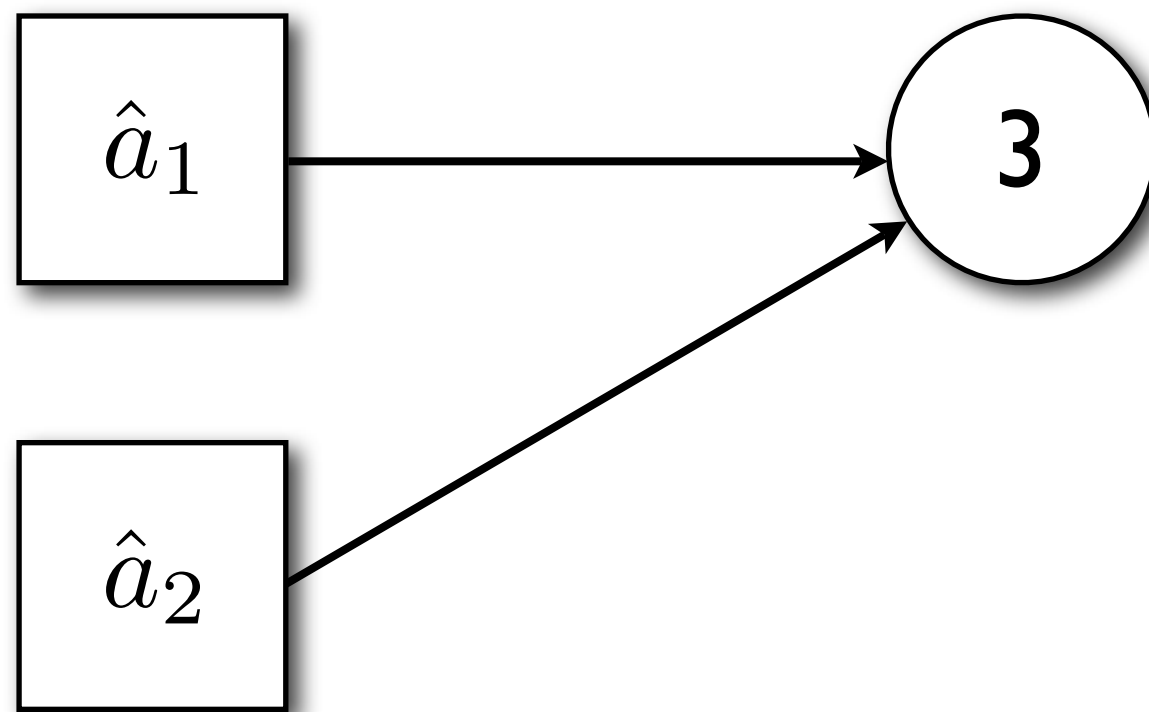
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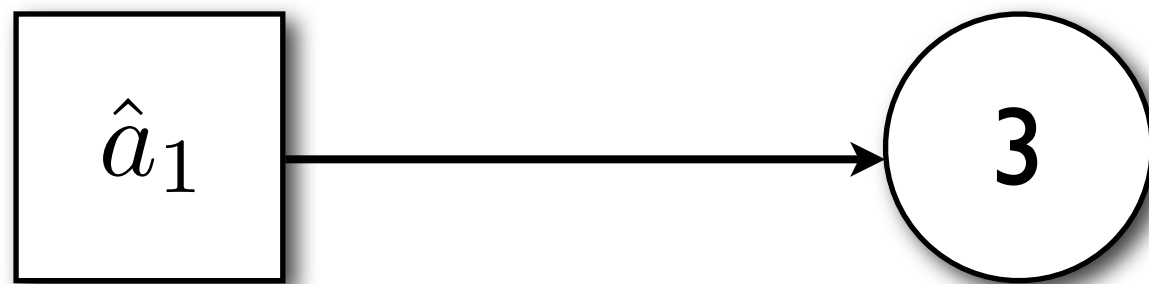
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# Dynamic Optimization

Given  $m$  abstract addresses,  
how should they be allocated  
to maximize precision?

# So, why not?

Can't within confines of standard recipe.

(Counter-example in paper.)

**Making it so**

# Making it so

- Factor allocation out of semantics.
- Make allocation nondeterministic.
- Prove nondeterministic allocation sound.

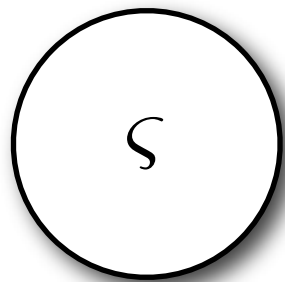
# Locative = Address

(But also times, bindings, contours, *etc.*)



# Factoring out allocation

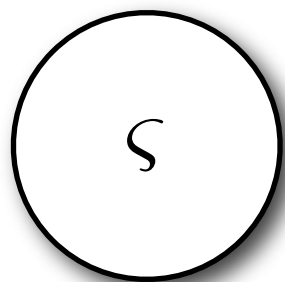
$$f : \textit{State} \longrightarrow \textit{State}$$



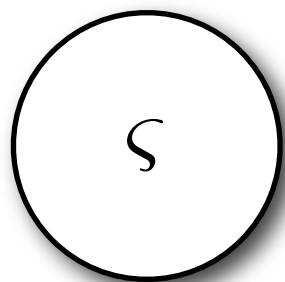
$$f : \textit{State} \longrightarrow \textit{State}$$



$$f : State \rightarrow State$$



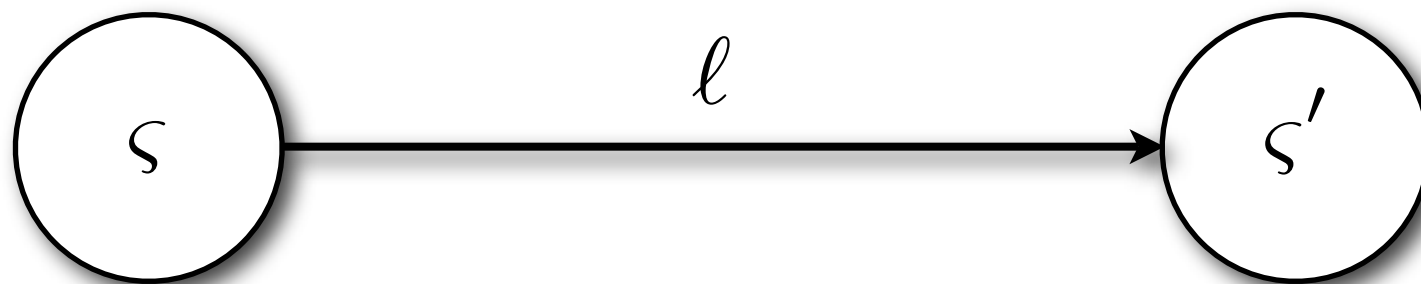
$$F : State \longrightarrow Loc \longrightarrow State$$



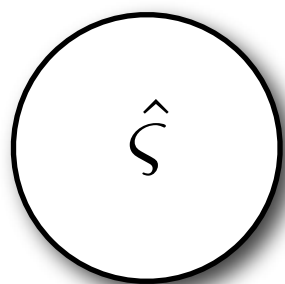
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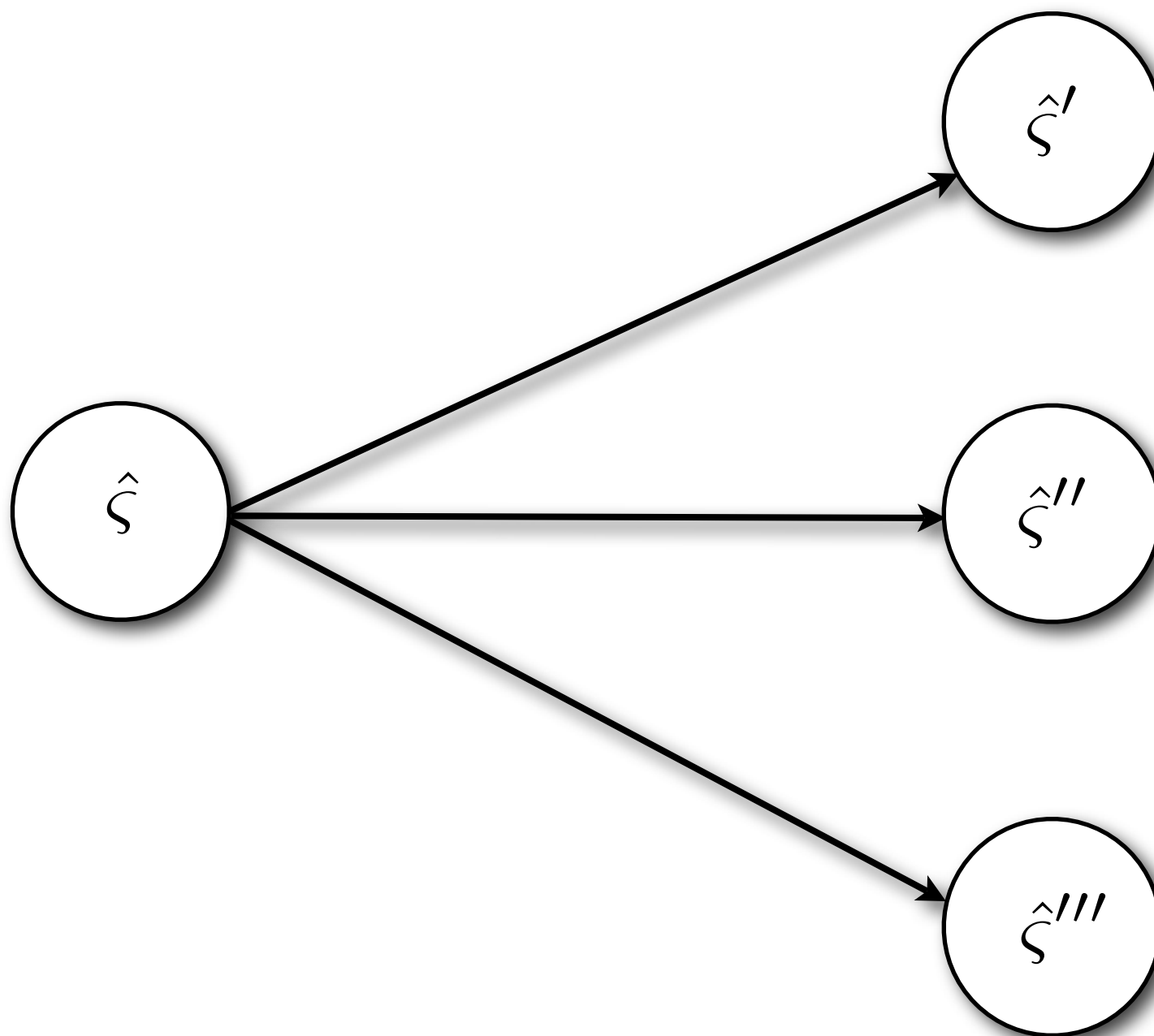


$$\hat{f} : \widehat{State} \rightarrow 2^{\widehat{State}}$$

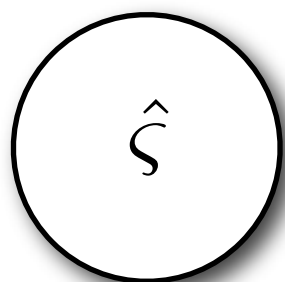




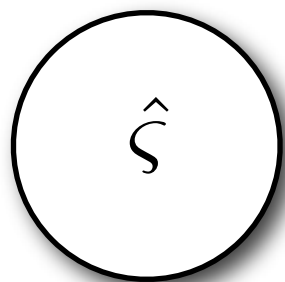
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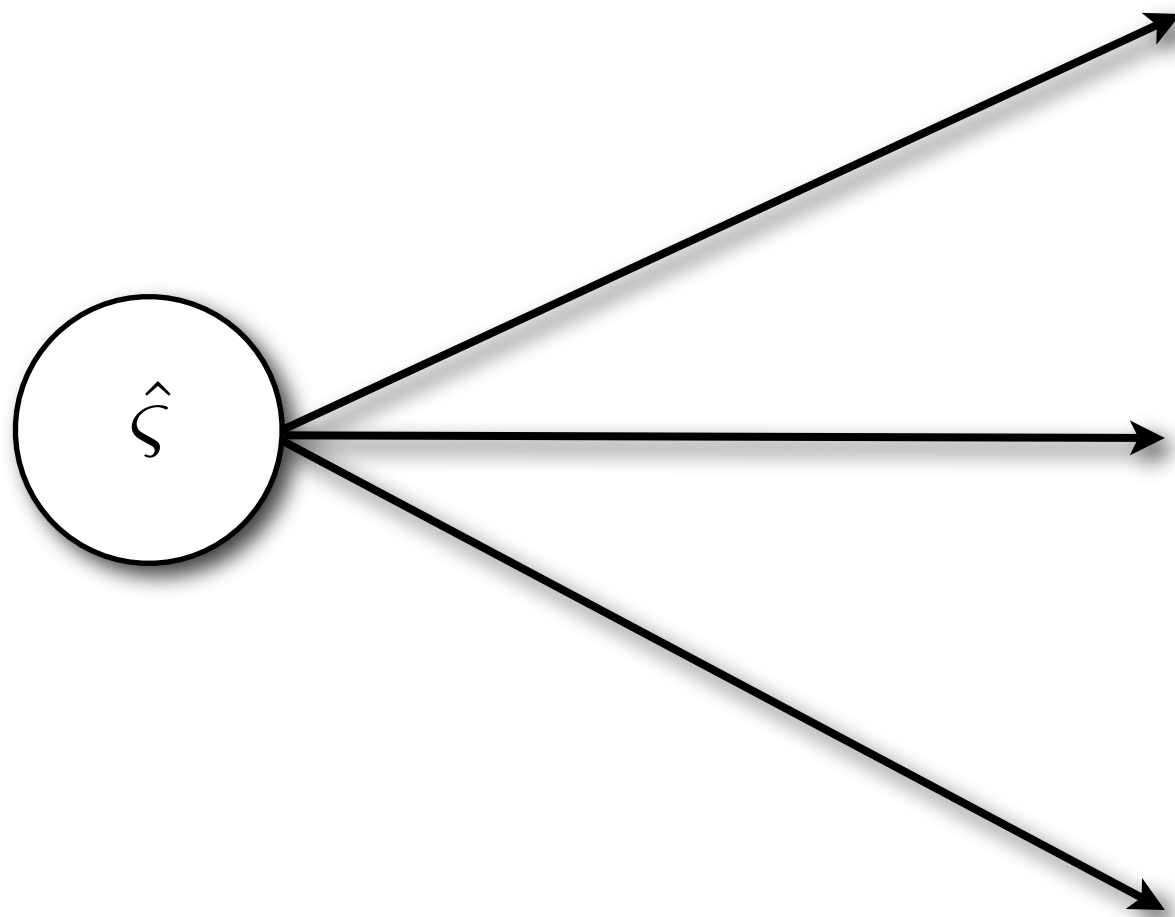
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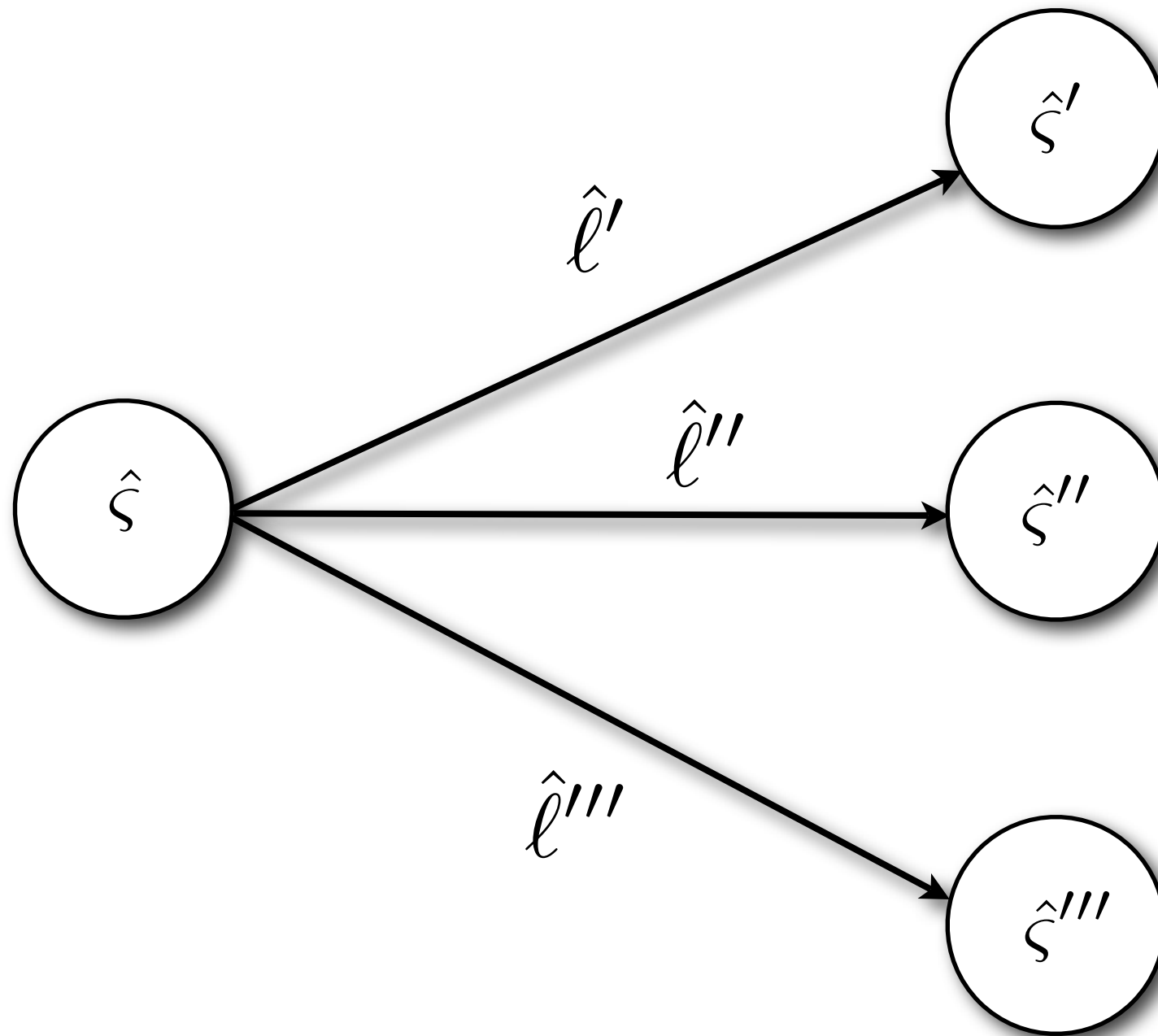
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# Nondeterministic Abstract Interpretation

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- Sealed abstract transition graphs.
- Factored abstraction maps.
- *A posteriori* soundness condition.

# Transition Graphs

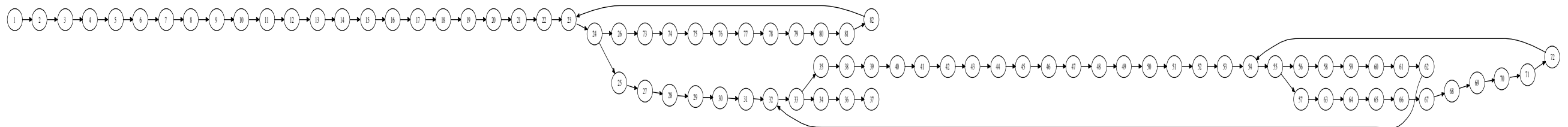
- Nodes = States
- Edge = Transition labeled by chosen locative



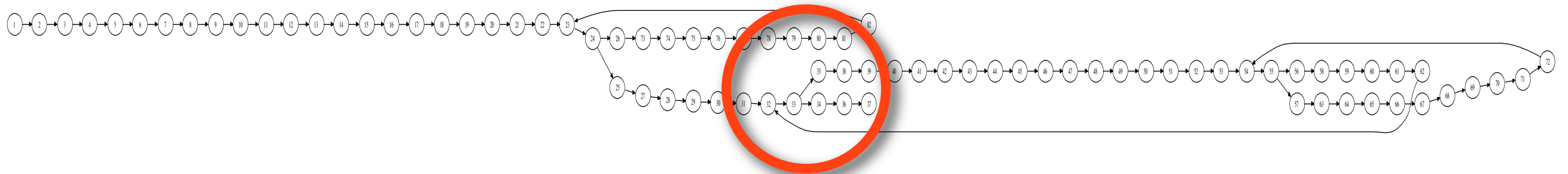
# Sealed Graphs

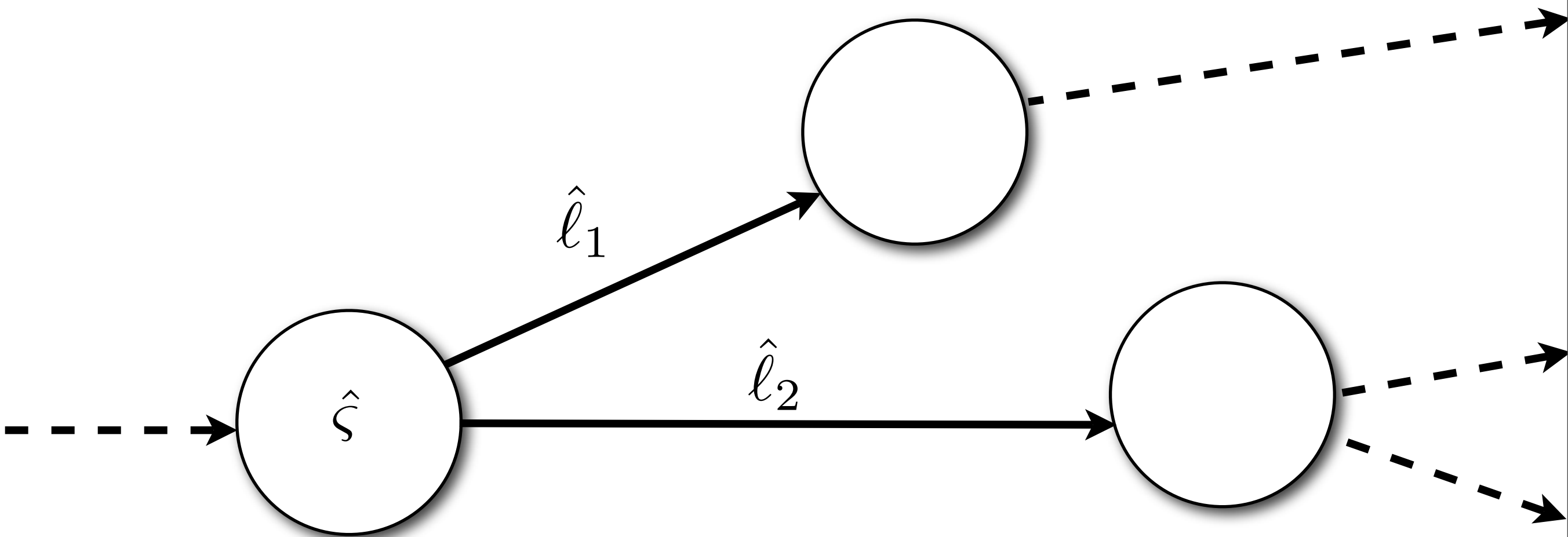
Graph is **sealed** under factored semantics iff every state has an edge to cover every transition.

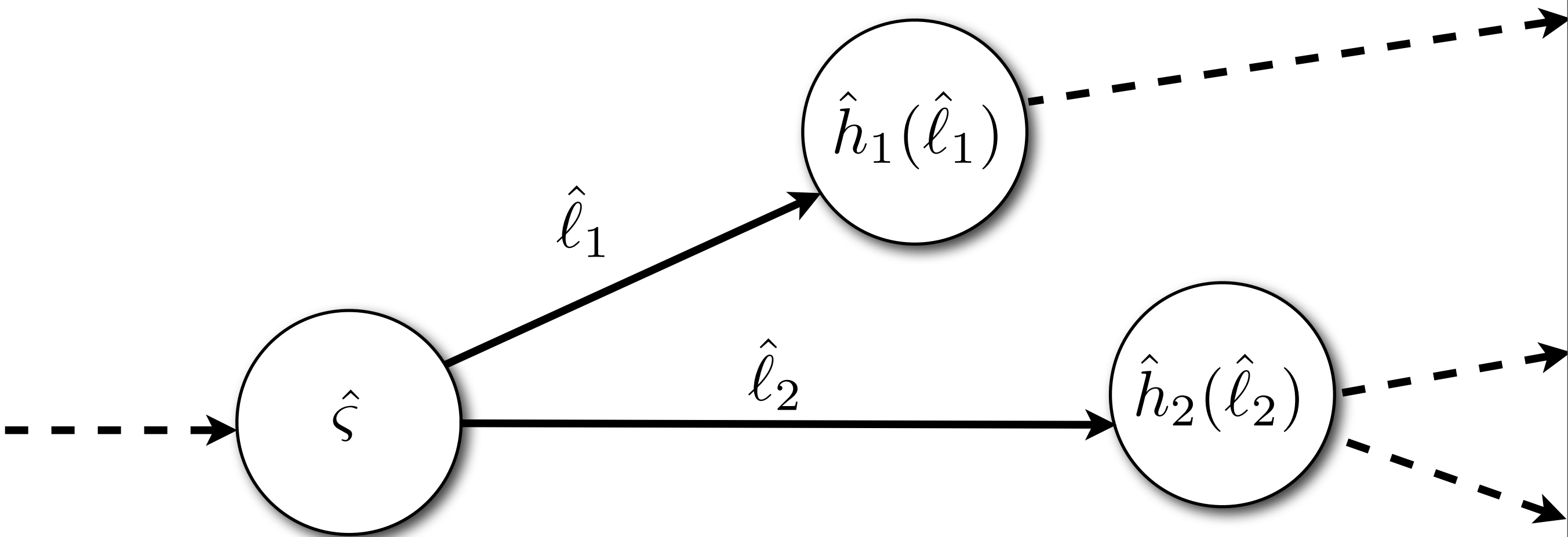
# Example: *Unsealed* Graph



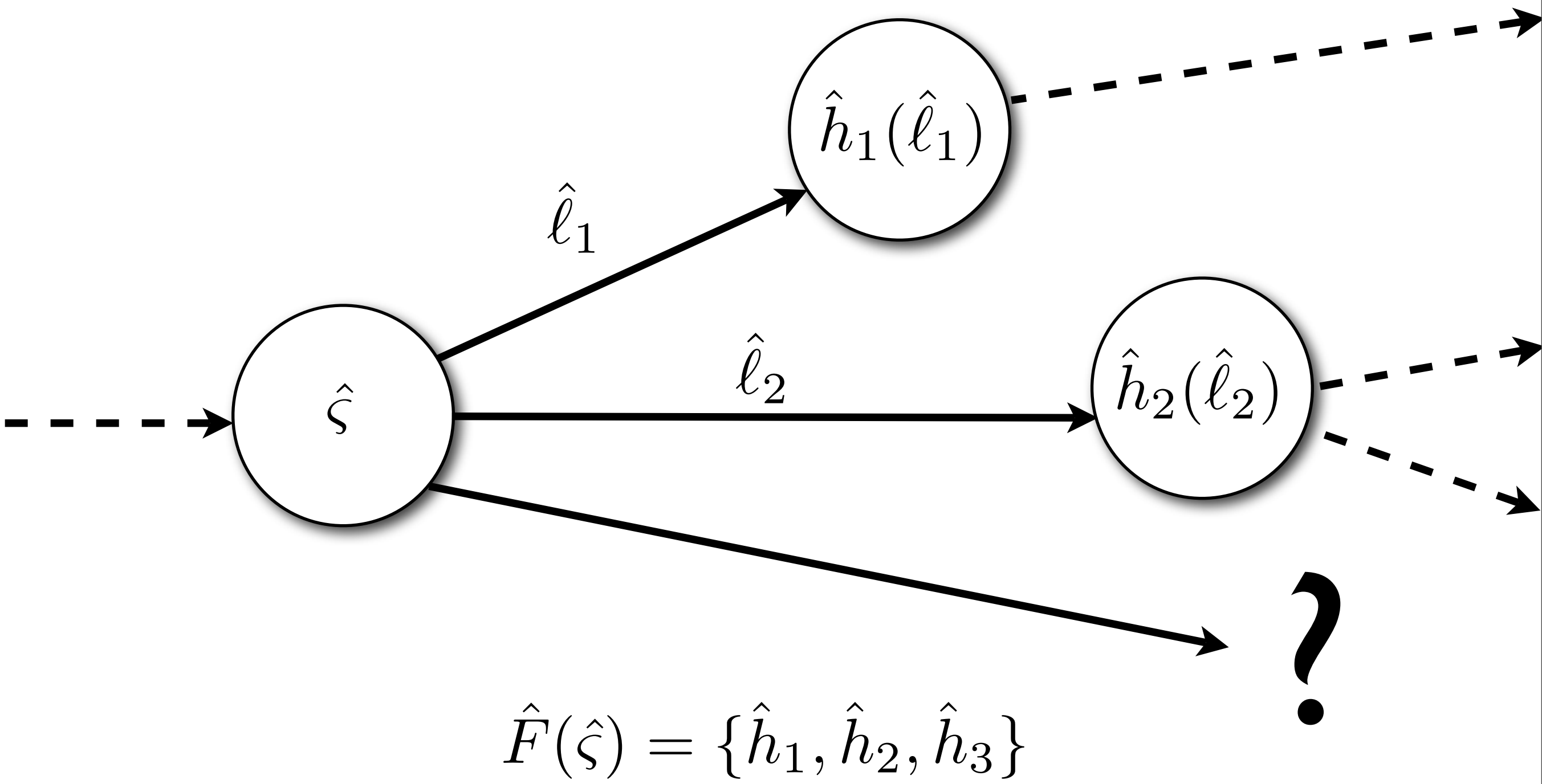
# Example: *Unsealed* Graph







$$\hat{F}(\hat{s}) = \{\hat{h}_1, \hat{h}_2, \hat{h}_3\}$$



# Proving Sealed Graphs Sound

# Factoring Abstraction

$$\alpha : State \rightarrow \widehat{State}$$



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$$\alpha : State \rightarrow \widehat{State}$$

$$\beta : (Loc \rightarrow \widehat{Loc}) \rightarrow (State \rightarrow \widehat{State})$$

# Dependent Simulation

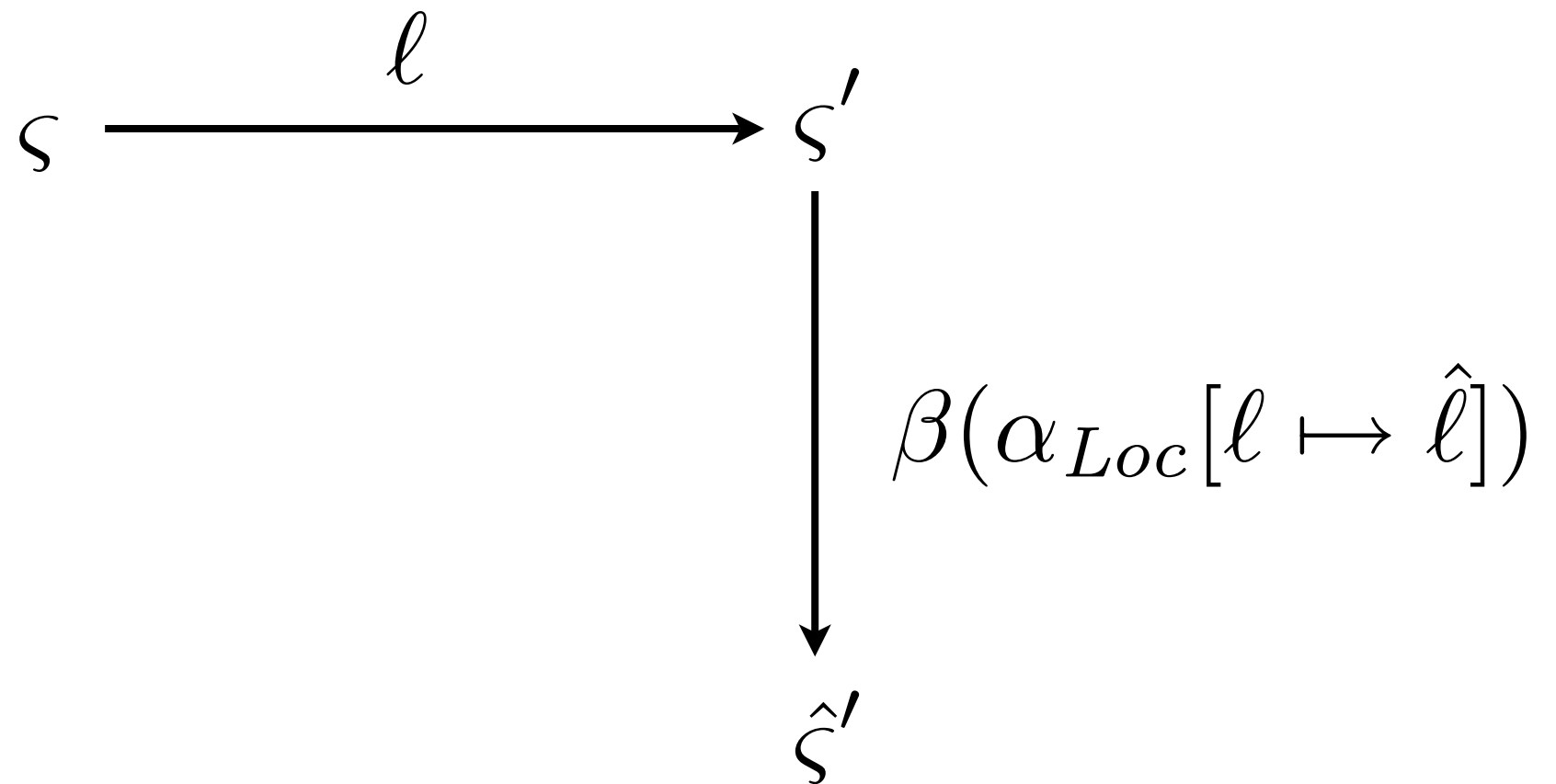
# Dependent Simulation

§

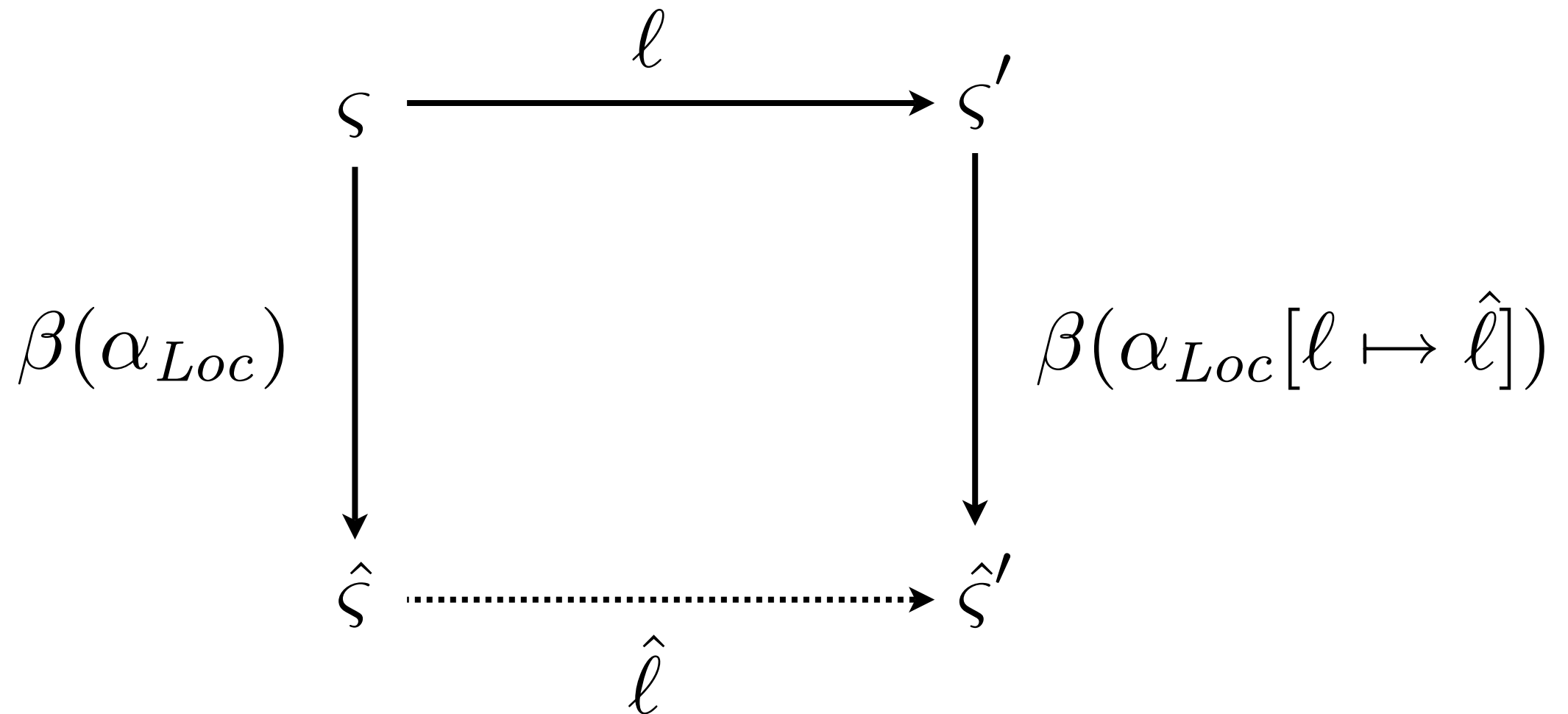
# Dependent Simulation

$$\varsigma \xrightarrow{\ell} \varsigma'$$

# Dependent Simulation



# Dependent Simulation



# *A Posteriori* Theorem

Dependent simulation  $\rightarrow$  Abstraction always exists

# Proof Highlights

- Reduces to existence of locative abstractor.
- Construct abstractor as limit of sequence:

$$\alpha_{Loc} = \lim_{i \rightarrow N} \alpha_{Loc}^i$$



# More in the paper

- Nondeterministic CFA:  $\exists$ CFA.
- More on greedy adaptive allocation.
- Discussion of global precision sensitivity.

# Ongoing Work

- Empirical trials: 1.5x - 3x space, time savings
- Genetic algorithms
- Probabilistic allocation

# So...

- Stop changing concrete semantics.
- Look beyond context for allocation.
- Don't allocate context if bad for precision.

**Thanks, y'all**