

A posteriori soundness for nondeterministic abstract interpretations

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- Questions you don't
- “But, why did you prove it *that* way?”
- want at your defense
- “But, why is that *necessary*?”
- “So, why *did* the Cousots do it that way?”

Nondeterministic Abstract Interpretation

- Where did it come from?
 - Frustration with the standard recipe.
- How do you prove it sound?
 - A *posteriori* proof technique.
- Why would you want to use it?
 - Better speed, better precision.

Outline

- Review standard recipe.
- Find annoyances.
- Get rid of them.

The As Posteriori Recipe

Define concrete state-space: L

Define concrete semantics: $f : L \rightarrow L$

Define abstract state-space: \hat{L}

Define abstraction map: $\alpha : \hat{L} \rightarrow L$

Define abstract semantics: $\hat{f} : \hat{L} \rightarrow \hat{L}$

Execute abstract semantics to obtain $\hat{\ell}' = \hat{f}(\hat{\ell})$.

Prove \hat{f} simulates f under α .

Prove $\hat{\ell}'$ simulates ℓ under α .

Illustrating the Standard Recipe

Malloc: The Language

labv ::= malloc()

Concrete Semantics

$$State = Instruction \times Store$$

Fresh

$$f(\llbracket v \Leftarrow \zeta' \text{ malloc}() \rrbracket : \vec{i}, \sigma) = (\vec{i}, \sigma[v \mapsto a'])$$

$$a' = \text{alloc}(\zeta) = \max(\text{range}(\sigma)) + 1$$

Abstract Semantics

$$\widehat{State} = \textit{Instruction} \times \widehat{Store}$$

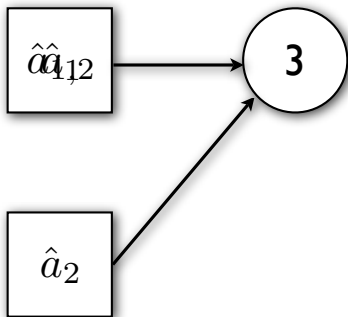
$$\hat{f}(\llbracket v := \text{malloc}() \rrbracket : \vec{i}, \hat{\sigma}) = (\vec{i}, \hat{\sigma}[v \mapsto \hat{a}])$$

$$\hat{a} = \widehat{\text{alloc}}(\hat{\varsigma}) \quad (\text{from some finite set})$$

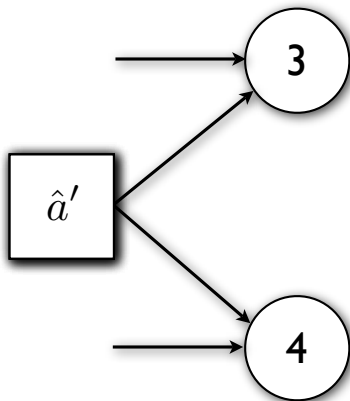
What to allocate?

- Abstract addresses = Scarce resource
- Avoid over-allocation: Good for speed
- Avoid under-allocation: Good for precision

Example: Over-allocation



Example: Under-allocation



Allocation heuristics

Observation: Objects from like contexts act alike.

Example: $\widehat{\text{alloc}}(\llbracket lab : \dots \rrbracket : \vec{i}, -) = lab$

Annoyance: Soundness

If

$$\alpha(\varsigma) \sqsubseteq \hat{\varsigma}$$

then

$$\alpha_{Addr}(\text{addr}(f(\varsigma))) \sqsubseteq \widehat{\text{addr}(f(\hat{\varsigma}))}$$

The Issue

$$\text{alloc}(_, \sigma) = \max(\text{range}(\sigma)) + 1$$

$$\widehat{\text{alloc}}(\llbracket lab : \dots \rrbracket : \vec{i}, _) = lab$$

What abstraction map will work here?

Example

A : x := malloc()

B : y := malloc()

$\sigma = [x \rightarrow 1, y \rightarrow 2]$

$\alpha_{Addr} = [1 \rightarrow A, 2 \rightarrow B]$

Standard Solution

Change the concrete semantics!

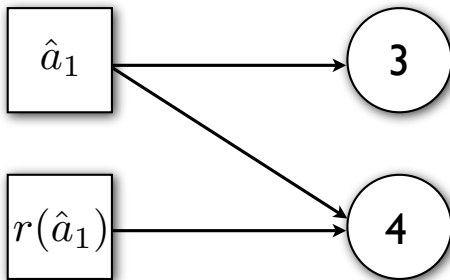
$\text{alloc}(\llbracket lab \rrbracket \sigma) = \text{min}(\text{range}(\sigma) + 1) + 1, lab)$

$\alpha(-, lab) = lab$

Another problem:
Heuristics sometimes
make stupid decisions
Why not adapt on the fly?

Example: Greedy Strategy

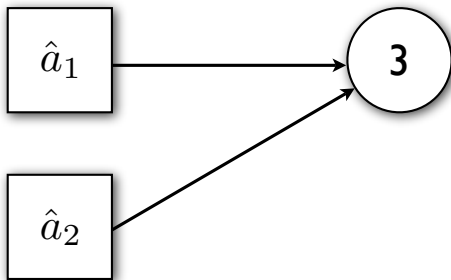
Heuristic says, “Allocate \hat{a}_1 , and bind 4.”



Adaptive allocator says, “Try $r(\hat{a}_1)$ first.”

Example: Greedy Strategy

Heuristic says, “Allocate \hat{a}_2 , and bind 3.”



Adaptive allocator says, “Just use \hat{a}_1 .”

Dynamic Optimization

Given m abstract addresses,
how should they be allocated
to maximize precision?

So, why not?

Can't within confines of standard recipe.

(Counter-example in paper.)

Making it so

- Factor allocation out of semantics.
- Make allocation nondeterministic.
- Prove nondeterministic allocation sound.

Locative = Address

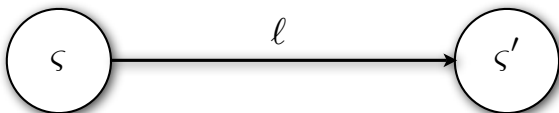
(But also times, bindings, contours, etc.)

Factoring out allocation

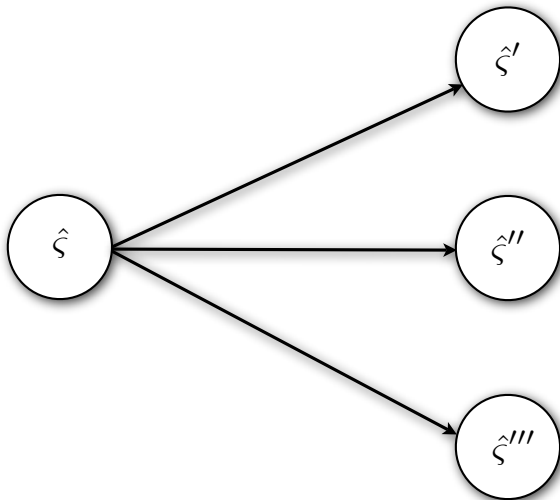
$$f : State \rightarrow State$$



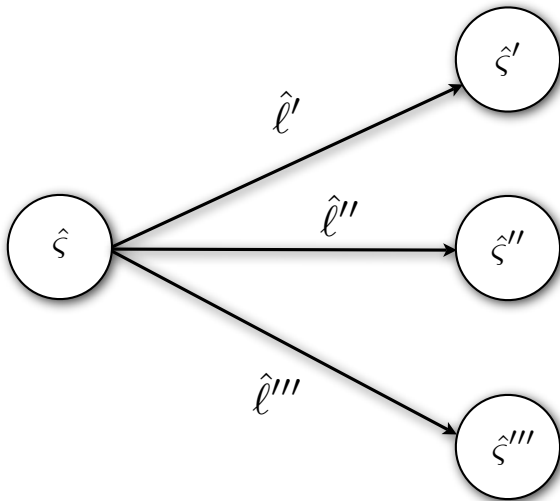
$$F : State \rightarrow Loc \rightarrow State$$



$$\hat{f} : \widehat{State} \rightarrow 2^{\widehat{State}}$$



$$\hat{F} : \widehat{State} \rightarrow 2^{\widehat{Loc} \rightarrow \widehat{State}}$$



- Nondeterministic
Sealed abstract transition graphs.

Abstract Interpretation

- Factored abstract transition maps
- A *posteriori* soundness condition.

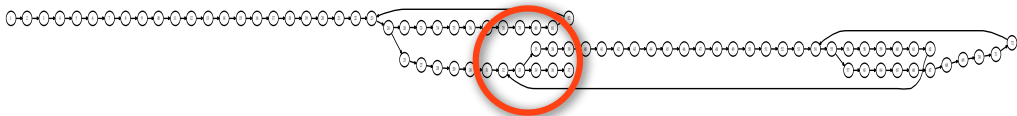
Transition Graphs

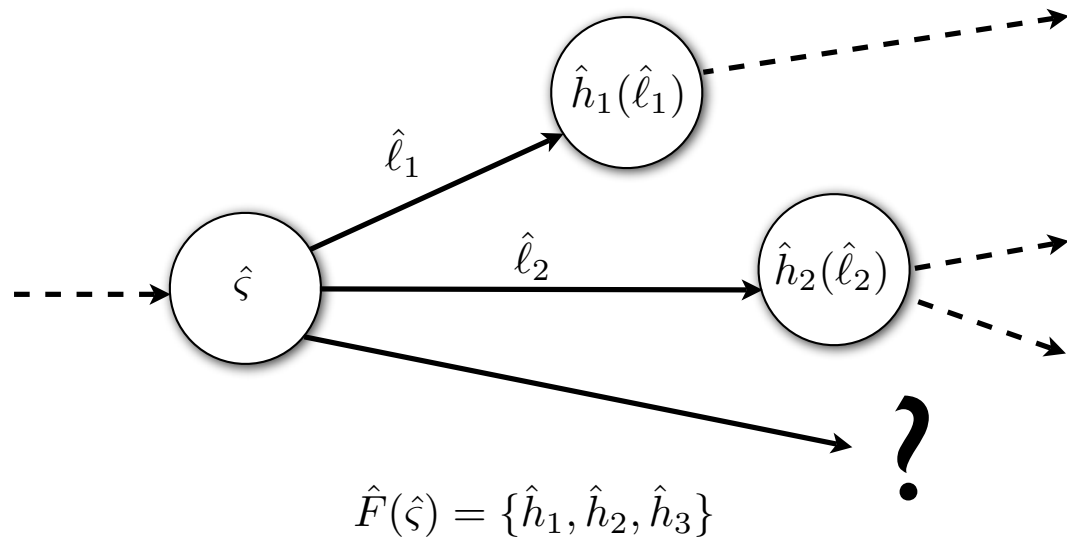
- Nodes = States
- Edge = Transition labeled by chosen locative

Sealed Graphs

Graph is **sealed** under factored semantics iff every state has an edge to cover every transition.

Example: *Unsealed* Graph





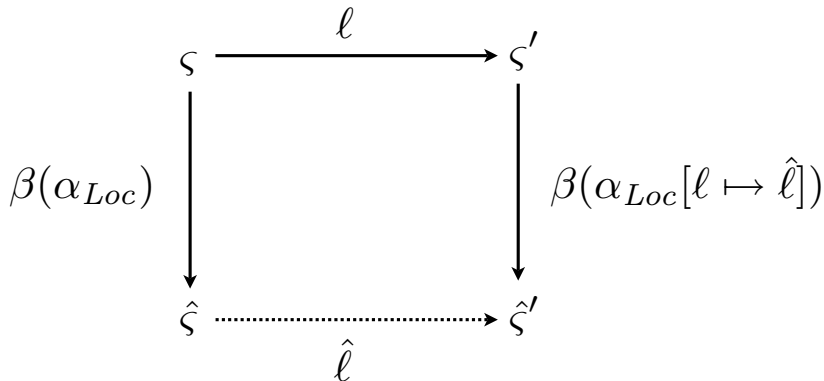
Proving Sealed Graphs Sound

Factoring Abstraction

$$\alpha : State \rightarrow \widehat{State}$$

$$\beta : (Loc \rightarrow \widehat{Loc}) \rightarrow (State \rightarrow \widehat{State})$$

Dependent Simulation



A Posteriori Theorem

Dependent simulation \rightarrow Abstraction always exists

Proof Highlights

- Reduces to existence of locative abstractor.
- Construct abstractor as limit of sequence:

$$\alpha_{Loc} = \lim_{i \rightarrow N} \alpha_{Loc}^i$$

More in the paper

- Nondeterministic CFA: \exists CFA.
- More on greedy adaptive allocation.
- Discussion of global precision sensitivity.

Ongoing Work

- Empirical trials: 1.5x - 3x space, time savings
- Genetic algorithms
- Probabilistic allocation

So...

- Stop changing concrete semantics.
- Look beyond context for allocation.
- Don't allocate context if bad for precision.

Thanks, y'all