

# Environment Analysis via $\Delta$ CFA

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# Control-flow analysis is not enough

## Problem

- ▶ Closure =  $\lambda$  term + environment;
- ▶ *e.g.*,  $(\lambda () x) + [x \mapsto 3]$
- ▶ CFA: good with control (what  $\lambda$  invoked from which call sites);
- ▶ ... not so good with environments.

## Control-flow analysis is not enough

```
(let ((f (λ (x h) (if (zero? x)
                      (h)
                      (λ () x))))))
  (f 0 (f 3 #f)))
```

**Fact:**  $(\lambda () x)$  flows to  $(h)$ .

**Question:** Safe to inline?

# Control-flow analysis is not enough

```
(let ((f (λ (x h) (if (zero? x)
                      (h)
                      (λ () x))))))
(f 0 (f 3 #f)))
```

**Fact:**  $(\lambda () x)$  flows to  $(h)$ .

**Question:** Safe to inline?

**Answer:** No.

**Why:** Only *one* variable  $x$  in program;  
but *multiple dynamic bindings*.

$(\lambda () x) + [x \mapsto 0]$

$v$ .

$(\lambda () x) + [x \mapsto 3]$

# Control-flow analysis is not enough

Folding infinite set of binding contours  
down to finite set causes merging.  
Can lead to unsound conclusions.

Problem:  $|x| = |y|$  does not imply  $x = y$

## Why it matters

We frequently use closures as general “carriers” of data:

- ▶ Create closure at point  $a$ .
- ▶ Ship to point  $b$  and invoke.

$a$  &  $b$  have same static scope and *same dynamic bindings*  $\Rightarrow$

- ▶ inline closure's code at  $b$  (super- $\beta$  inlining),
- ▶ communicate data via shared context.

Avoid heap allocating & fetching data.

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Avoid heap allocating & fetching data.

**Need to reason about environment relationships  
between two control points.**

# Tool 1: Procedure strings

## Classic model (Sharir & Pnueli, Harrison)

- ▶ Program trace at procedure level
- ▶ String of procedure activation/deactivation actions

## Actions

control: call/return

Intuition: call extends environment; return restores environment.



# Tool 1: Procedure strings

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## Actions

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Intuition: call extends environment; return restores environment.

(fact 1)

```
call fact / call zero? / return zero? / call - / return - /  
call fact / call zero? / return zero? / return fact /  
call * / return * / return fact
```

Note: Call/return items nest like parens.

# Problems with procedure strings

- ▶ In functional languages, not all calls have matching returns. (e.g., iteration)
- ▶ Procedure strings designed for “large-grain” procedures.
- ▶ What about other control/env operators? (loops, conditionals, coroutines, continuations, . . .)

## Tool 2: CPS

$\lambda$  is universal representation of control & env.

Construct	encoding
fun call	call to $\lambda$

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exception	call to $\lambda$



## Tool 2: CPS

$\lambda$  is universal representation of control & env.

Construct	encoding
fun call	call to $\lambda$
fun return	call to $\lambda$
iteration	call to $\lambda$
sequencing	call to $\lambda$
conditional	call to $\lambda$
exception	call to $\lambda$
coroutine	call to $\lambda$
$\vdots$	$\vdots$

Now  $\lambda$  is fine-grained construct.

Adapt procedure-string models to CPS  $\Rightarrow$   
have universal analysis.

# CPS & stacks

But wait! CPS is all calls, no returns!

Procedure strings won't nest properly:

call a / call b / call c / call d / ...

# CPS & stacks

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Procedure strings won't nest properly:

call a / call b / call c / call d / ...

Unless...

# CPS & stacks

## Solution

- ▶ Syntactically partition CPS language into “user” & “continuation” world.

We still have calls & returns;  
have just decoupled them somewhat.

- ▶ Shift from call/return view  
to push/pop view.

Calls & returns no longer nest,  
but pushes & pops *always* nest.

## Example: recursive factorial

```
(λ (n)
  (letrec ((f (λ (m)
                (if0 m 1
                    (* m (f (- m 1)))))))
    (f n)))
```

## Example: recursive factorial

```
( $\lambda_t$  (n ktop)
  (letrec ((f ( $\lambda_f$  (m k)
              (%if0 m
                ( $\lambda_1$  () (k 1))
                ( $\lambda_2$  ()
                  (- m 1 ( $\lambda_3$  (m2)
                                (f m2 ( $\lambda_4$  (a)
                                             (* m a k)
                                             ))))))))
            (f n ktop))))
```

## Example: recursive factorial

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( $\lambda_t$  (n ktop)
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                                             (* m a k)
                                             ))))))))
            (f n ktop))))
```

But...

Blue  $\neq$  call/push

Red  $\neq$  return/pop

# Putting it all together: frame strings

## Frame strings, $F$

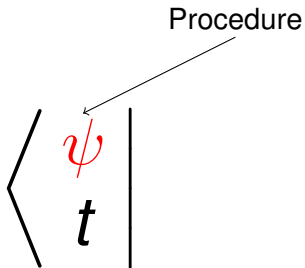
- ▶ Record push/pop sequences.
- ▶ Each character: push or pop.
- ▶ Calls push frames.
- ▶ Continuations restore stacks.



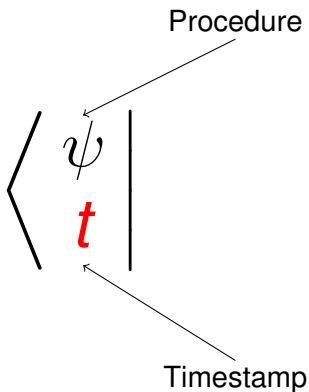
# Anatomy of a push character

$$\left\langle \begin{array}{c} \psi \\ \mathbf{t} \end{array} \right|$$

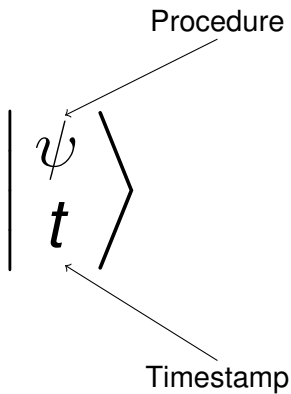
# Anatomy of a push character



# Anatomy of a push character



# Anatomy of a pop character



# Net & inverse operators

## Net

- ▶ Written  $[p]$ .
- ▶ Cancels opposite neighbors.

## Examples

- ▶  $[ \langle \frac{a}{6} | \langle \frac{b}{7} | \frac{b}{7} \rangle | \frac{a}{6} \rangle ] = \epsilon$
- ▶  $[ | \frac{q}{38} \rangle \langle \frac{q}{38} | ] = \epsilon$
- ▶  $[ \langle \frac{r}{21} | \frac{r}{21} \rangle \langle \frac{a}{71} | ] = \langle \frac{a}{71} |$

# Net & inverse operators

## Net

- ▶ Written  $[p]$ .
- ▶ Cancels opposite neighbors.

## Examples

- ▶  $[\langle a|_6 \langle b|_7 | b \rangle_7 | a \rangle_6] = \epsilon$
- ▶  $[\langle q|_{38} \langle q|_{38}] = \epsilon$
- ▶  $[\langle r|_{21} | r \rangle_{21} \langle a|_{71}] = \langle a|_{71}$

## Two views

**Absolute**  $[p_t]$  is picture of stack at time  $t$ .

**Relative**  $[p_t^{t'}]$  is summary of stack change.

# Net & inverse operators

$p^{-1}$  = reverse  $[p]$  and swap “push” & “pop”:

## Example

$$(\langle a| \langle b| \langle b| \langle c|)^{-1} = |c\rangle |a\rangle$$

Frame strings mod  $[\cdot]$  is group:  $p + p^{-1} \equiv p^{-1} + p \equiv \epsilon$ .  
(+ is concatenation)

# The inverse operator

Use: restoring stack to previous state

Time	Frame string	Stack
$t_1$	$p$	$[p]$
$t_2$	$p + q$	$[p + q]$
$t_3$	$p + q + ???$	$[p]$



# The inverse operator

Use: restoring stack to previous state

Time	Frame string	Stack
$t_1$	$p$	$[p]$
$t_2$	$p + q$	$[p + q]$
$t_3$	$p + q + q^{-1}$	$[p]$

This is what continuations do in CPS...  
but expressed in terms of *change*.

# Iterative factorial example

```
(λt (n ktop)
  (letrec ((f (λf (m a k)
    (%if0 m
      (λ1 () (k a))
      (λ2 ()
        (- m 1 (λ3 (m2)
          (* m a (λ4 (a2)
            (f m2 a2 k)
            )))))))))
  (f n 1 ktop)))
```

Call site	Description	Stack Δ	Stack
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  (letrec ((f ( $\lambda_f$  (m a k)
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    (f n 1 ktop)))
```

Call site	Description	Stack $\Delta$	Stack
			$\langle \uparrow \mid 1 \rangle$

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( $\lambda_t$  (n ktop)
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```

Call site	Description	Stack $\Delta$	Stack
(f n 1 ktop)	tail call to $\lambda_f$	$ ^t_1\rangle\langle^f_2 $	$\langle^t_1 $ $\langle^f_2 $

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```

Call site	Description	Stack $\Delta$	Stack
(f n 1 ktop)	tail call to $\lambda_f$	$ _1\rangle\langle^f_2 $	$\langle^t_1 $
(%if0 m ...)	call to %if0	$\langle^{%if0}_3 $	$\langle^f_2 \langle^{%if0}_3 $

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```

Call site	Description	Stack $\Delta$	Stack
(f n 1 ktop)	tail call to $\lambda_f$	$\langle 1 \rangle \langle 2 \mid$	$\langle 1 \mid$
(%if0 m ...)	call to %if0	$\langle 3 \mid$	$\langle 2 \mid \langle 3 \mid$
%if0 <i>internal</i>	return to $\lambda_2$	$\langle 3 \mid \langle 2 \mid$	$\langle 2 \mid \langle 4 \mid$

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%if0 <i>internal</i>	return to $\lambda_2$	$\langle 3 \mid \langle 2 \mid$	$\langle 2 \mid \langle 4 \mid$
(- m 1 ...)	call to -	$\langle 5 \mid$	$\langle 2 \mid \langle 4 \mid \langle 5 \mid$

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```

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			$\langle t \mid$
(f n 1 ktop)	tail call to $\lambda_f$	$\mid 1 \rangle \langle f \mid$	$\langle f \mid$
(%if0 m ...)	call to %if0	$\langle 3 \mid$	$\langle f \mid \langle \%if0 \mid$
%if0 <i>internal</i>	return to $\lambda_2$	$\mid 3 \rangle \langle 2 \mid$	$\langle f \mid \langle 2 \mid$
(- m 1 ...)	call to -	$\langle 5 \mid$	$\langle f \mid \langle 2 \mid \langle 4 \mid \langle 5 \mid$
- <i>internal</i>	return to $\lambda_3$	$\mid 5 \rangle \langle 3 \mid$	$\langle f \mid \langle 2 \mid \langle 3 \mid$



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                                              ))))))))
    (f n 1 ktop)))
```

Call site	Description	Stack $\Delta$	Stack
(f n 1 ktop)	tail call to $\lambda_f$	$ 1\rangle\langle 2 $	$\langle 1 $ $\langle 2 $
(%if0 m ...)	call to %if0	$\langle 3 $	$\langle 2 $ $\langle 3 $
%if0 <i>internal</i>	return to $\lambda_2$	$\langle 3 $ $\langle 2 $	$\langle 2 $ $\langle 4 $
(- m 1 ...)	call to -	$\langle 5 $	$\langle 2 $ $\langle 4 $ $\langle 5 $
- <i>internal</i>	return to $\lambda_3$	$ 5\rangle\langle 3 $	$\langle 2 $ $\langle 4 $ $\langle 3 $
(* m a ...)	call to *	$\langle * $	$\langle 2 $ $\langle 4 $ $\langle 3 $ $\langle * $

# Iterative factorial example

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( $\lambda_t$  (n ktop)
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                                                (f m2 a2 k)
                                                ))))))))
          (f n 1 ktop))))
```

Call site	Description	Stack $\Delta$	Stack
(f n 1 ktop)	tail call to $\lambda_f$	$ 1\rangle\langle 2 $	$\langle 1 $ $\langle 2 $
(%if0 m ...)	call to %if0	$\langle 3 $	$\langle 2  \langle 3 $
%if0 <i>internal</i>	return to $\lambda_2$	$ 3\rangle\langle 4 $	$\langle 2  \langle 4 $
(- m 1 ...)	call to -	$\langle 5 $	$\langle 2  \langle 4  \langle 5 $
- <i>internal</i>	return to $\lambda_3$	$ 5\rangle\langle 6 $	$\langle 2  \langle 4  \langle 6 $
(* m a ...)	call to *	$\langle 7 $	$\langle 2  \langle 4  \langle 6  \langle 7 $
* <i>internal</i>	return to $\lambda_4$	$ 7\rangle\langle 8 $	$\langle 2  \langle 4  \langle 6  \langle 8 $

# Iterative factorial example

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( $\lambda_t$  (n ktop)
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Call site	Description	Stack $\Delta$	Stack
(f n 1 ktop)	tail call to $\lambda_f$	$ 1\rangle\langle 2 $	$\langle 1 $ $\langle 2 $
(%if0 m ...)	call to %if0	$\langle 3 $	$\langle 2  \langle 3 $
%if0 <i>internal</i>	return to $\lambda_2$	$\langle 3  \langle 2 $	$\langle 2  \langle 4 $
(- m 1 ...)	call to -	$\langle 5 $	$\langle 2  \langle 4  \langle 5 $
- <i>internal</i>	return to $\lambda_3$	$\langle 5  \langle 3 $	$\langle 2  \langle 4  \langle 6 $
(* m a ...)	call to *	$\langle 7 $	$\langle 2  \langle 4  \langle 6  \langle 7 $
* <i>internal</i>	return to $\lambda_4$	$\langle 7  \langle 4 $	$\langle 2  \langle 4  \langle 6  \langle 8 $
(f m2 a2 k)	tail call to $\lambda_f$	$\langle 4  \langle 3  \langle 2  \langle 1 $	$\langle 9 $

# Adding frame strings to concrete CPS semantics

## Key steps

- ▶ Give states time stamps.
- ▶ Give states frame-string log,  $\delta : Time \rightarrow F$ .  
Log is “relative” definition.  
(Just what we need!)
- ▶ Give values “birthdates”: creation time stamps.

## Example

If  $\delta_{13}$  is the log from time 13, then  $\delta_{13}(7)$  is the frame-string change between time 7 and time 13.

## To invoke continuation with birthday $t_b$

Perform  $\delta(t_b)^{-1}$  on stack.

(That is, add  $\delta(t_b)^{-1}$  to frame string.)

## Interval notation for frame-string change

$$[t, t'] = \delta_{t'}(t)$$

That is,  $[t, t']$  is the frame-string change between time  $t$  and  $t'$ .

# A taste of environment theory

## Theorem (Pinching Lemma)

*No stack change between two times iff the times the same.*

$$[[t_1, t_2]] = \epsilon \iff t_1 = t_2.$$

## Theorem

*Environments separated by continuation frame actions differ by the continuations' bindings.*

$$[[t_0, t_2] + [t_1, t_2]^{-1}] = |\gamma_1\rangle \dots |\gamma_n\rangle \langle \gamma'_1| \dots \langle \gamma'_n| \Rightarrow \beta_{t_1} |\overline{\mathbf{B}(\vec{\gamma}')}\rangle = \beta_{t_0} |\overline{\mathbf{B}(\vec{\gamma})}\rangle.$$

*(Notes:  $\beta$ 's represent environments; inferring  $t_0/t_1$  environment relationship from log at time  $t_2$ .)*

# Building $\Delta$ CFA

## $\Delta$ CFA

- ▶ Straightforward abstract interpretation.
- ▶ Extends Harrison's abstract procedure strings.

## Abstract frame strings

- ▶ Map from procedure to net change in procedure.
- ▶ Net change described by finite set of regular expressions.

$$\hat{F} = \text{ProcedureLabels} \rightarrow \mathcal{P}(\Delta)$$

$$\Delta = \{\epsilon, \langle \cdot |, | \cdot \rangle, \langle \cdot | \langle \cdot |^+, | \cdot \rangle | \cdot \rangle^+, | \cdot \rangle^+ \langle \cdot |^+ \}$$

# $\Delta$ CFA: Eval

$$\frac{(\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \beta, ve, \ t) \Rightarrow (proc, \mathbf{d}, \mathbf{c}, ve, \ t)}{\text{where } \begin{cases} proc = \mathcal{A} \beta \ ve \ t \ f \\ d_i = \mathcal{A} \beta \ ve \ t \ e_i \\ c_j = \mathcal{A} \beta \ ve \ t \ q_j \end{cases}}$$



## $\Delta$ CFA: Eval

$$\overline{(\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \beta, \mathbf{ve}, \delta, t)} \Rightarrow (\mathit{proc}, \mathbf{d}, \mathbf{c}, \mathbf{ve}, \delta', t)$$

where

$$\left\{ \begin{array}{l} \mathit{proc} = \mathcal{A} \beta \ \mathit{ve} \ t \ f \\ d_i = \mathcal{A} \beta \ \mathit{ve} \ t \ e_i \\ c_j = \mathcal{A} \beta \ \mathit{ve} \ t \ q_j \\ \nabla_{\zeta} = \begin{cases} (\mathit{age}_{\delta} \ \mathit{proc})^{-1} & f \in \mathit{EXPC} \\ (\mathit{youngest}_{\delta} \ \mathbf{c})^{-1} & \text{otherwise} \end{cases} \\ \delta' = \delta + (\lambda t. \nabla_{\zeta}) \end{array} \right.$$

# $\Delta$ CFA: Eval

$$\overline{(\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \widehat{\beta}, \widehat{ve}, \widehat{\delta}, \widehat{t})} \rightsquigarrow (\widehat{proc}, \widehat{\mathbf{d}}, \widehat{\mathbf{c}}, \widehat{ve}, \widehat{\delta}', \widehat{t})$$

where

$$\left\{ \begin{array}{l} \widehat{proc} \in \widehat{\mathcal{A}} \widehat{\beta} \widehat{ve} \widehat{t} f \\ \widehat{d}_i = \widehat{\mathcal{A}} \widehat{\beta} \widehat{ve} \widehat{t} e_i \\ \widehat{c}_i = \widehat{\mathcal{A}} \widehat{\beta} \widehat{ve} \widehat{t} q_i \\ \Delta \widehat{p} = \begin{cases} (\widehat{age}_{\widehat{\delta}} \{ \widehat{proc} \})^{-1} & f \in EXPC \\ (\widehat{youngest}_{\widehat{\delta}} \widehat{\mathbf{c}})^{-1} & \text{otherwise} \end{cases} \\ \widehat{\delta}' = \widehat{\delta} \oplus (\lambda \widehat{t}. \Delta \widehat{p}) \end{array} \right.$$

## $\Delta$ CFA: Apply

$$\frac{\text{length}(\mathbf{d}) = \text{length}(\mathbf{u}) \quad \text{length}(\mathbf{c}) = \text{length}(\mathbf{k})}{((\llbracket \lambda_{\psi} (u^* k^*) \text{ call} \rrbracket, \beta, t_b), \mathbf{d}, \mathbf{c}, \text{ve}, t) \Rightarrow (\text{call}, \beta', \text{ve}', t')}$$

where  $\left\{ \begin{array}{l} t' = \text{tick}(t) \\ \beta' = \beta[u_i \mapsto t', k_j \mapsto t'] \\ \text{ve}' = \text{ve}[(u_i, t') \mapsto d_i, (k_j, t') \mapsto c_j] \end{array} \right.$

## $\Delta$ CFA: Apply

$$\frac{\text{length}(\mathbf{d}) = \text{length}(\mathbf{u}) \quad \text{length}(\mathbf{c}) = \text{length}(\mathbf{k})}{((\llbracket \lambda_{\psi} (u^* k^*) \text{ call} \rrbracket, \beta, t_b), \mathbf{d}, \mathbf{c}, \mathbf{ve}, \delta, t) \Rightarrow (\text{call}, \beta', \mathbf{ve}', \delta', t')}$$

where  $\left\{ \begin{array}{l} t' = \text{tick}(t) \\ \beta' = \beta[u_i \mapsto t', k_j \mapsto t'] \\ \mathbf{ve}' = \mathbf{ve}[(u_i, t') \mapsto d_i, (k_j, t') \mapsto c_j] \\ \nabla_{\zeta} = \langle \psi |_{t'} \\ \delta' = (\delta + (\lambda t. \nabla_{\zeta}))[t' \mapsto \epsilon] \end{array} \right.$

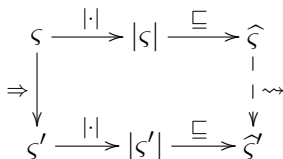
# $\Delta$ CFA: Apply

$$\frac{\text{length}(\widehat{\mathbf{d}}) = \text{length}(\mathbf{u}) \quad \text{length}(\widehat{\mathbf{c}}) = \text{length}(\mathbf{k})}{((\llbracket \mathcal{A}_\psi (u^* k^*) \text{ call} \rrbracket, \widehat{\beta}, \widehat{t}_b), \widehat{\mathbf{d}}, \widehat{\mathbf{c}}, \widehat{\mathbf{ve}}, \widehat{\delta}, \widehat{t}) \rightsquigarrow (\text{call}, \widehat{\beta}', \widehat{\mathbf{ve}}', \widehat{\delta}', \widehat{t}')} \\ \text{where } \begin{cases} \widehat{t}' = \widehat{\text{tick}}(\widehat{t}) \\ \widehat{\beta}' = \widehat{\beta}[u_i \mapsto \widehat{t}', k_j \mapsto \widehat{t}'] \\ \widehat{\mathbf{ve}}' = \widehat{\mathbf{ve}} \sqcup [(u_i, \widehat{t}') \mapsto \widehat{d}_i, (k_j, \widehat{t}') \mapsto \widehat{c}_j] \\ \Delta \widehat{\rho} = |\langle \widehat{\gamma}' \rangle| \\ \widehat{\delta}' = (\widehat{\delta} \oplus (\lambda \widehat{t}. \Delta \widehat{\rho})) \sqcup [\widehat{t}' \mapsto |\epsilon|] \end{cases}$$

# Correctness of $\Delta$ CFA

## Theorem

*$\Delta$ CFA simulates the concrete semantics.*



## Concrete super- $\beta$ inlining condition

When is it safe to inline  $\lambda$  term  $\psi'$  at call site  $\kappa'$ ?

- ▶ All calls at  $\kappa'$  are to  $\psi'$ .
- ▶ Environment in closure  $\equiv$  environment at  $\kappa'$ .

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$Inlinable((\kappa', \psi'), pr) \iff$

$\forall (\llbracket (f\ e^*\ q^*)_{\kappa} \rrbracket, \beta, ve, \delta, t) \in \mathcal{V}(pr) :$   
if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \beta_b, t_b) = \mathcal{A}\beta\ ve\ t\ f$   
then  $\begin{cases} \psi = \psi' \\ \beta_b | free(L_{pr}(\psi')) = \beta | free(L_{pr}(\psi')) \end{cases}$



# Correctness of super- $\beta$ inlining

## Theorem

*Inlining under Super- $\beta$  condition does not change meaning.*

## Sketch of Proof.

### Definition of $R$

$$\begin{array}{ccccc} \varsigma & \xrightarrow{\|\cdot\|} & \|\varsigma\| & \xleftarrow{\|\cdot\|} & \mathbf{S}^{-1}\varsigma\mathbf{S} \\ \mathbf{S} \downarrow & & & & \uparrow \mathbf{S}^{-1} \\ \mathbf{S}\varsigma & \xrightarrow{\|\cdot\|} & \|\mathbf{S}\varsigma\| & \xleftarrow{\|\cdot\|} & \varsigma\mathbf{S} \end{array}$$

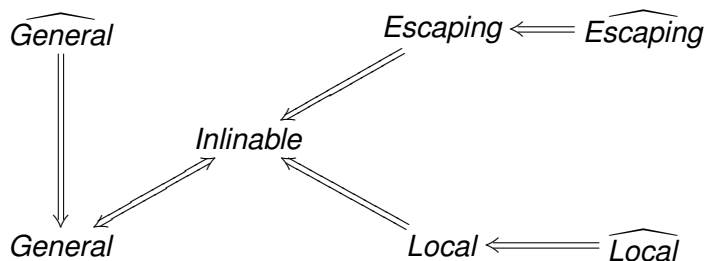
### Bisimulation Relation

$$\begin{array}{ccc} \varsigma & \xrightarrow{R} & \varsigma\mathbf{S} \\ \Rightarrow \downarrow & & \downarrow \Rightarrow \\ \varsigma' & \xrightarrow{R} & \varsigma'\mathbf{S} \end{array}$$

commutes.



## Some $\Delta$ CFA super- $\beta$ conditions



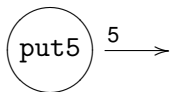
# Implementation

- ▶ 3500 lines of Haskell.
- ▶ Direct-style front end for small Scheme.
- ▶ Choice of stack behavior models.
- ▶ Super- $\beta$  inlining.
- ▶  $\beta/\eta$ -reduction.
- ▶ Useless-variable elimination.
- ▶ Dead-code elimination.
- ▶ Sparse conditional constant propagation.
- ▶ Optimizes/fuses loops and co-routines.

# A quick example: transducer/coroutine fusion

## The put5 transducer

```
(letrec ((put5 (λ (chan)
                 (let ((chan (put 5 chan)))
                     (put5 chan))))))
  put5)
```



# A quick example: transducer/coroutine fusion

## The doubler transducer

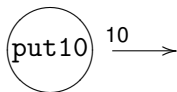
```
(letrec ((doubler (λ (uchan dchan)
                  (let* (((x uchan) (get uchan))
                        (dchan      (put (* 2 x) dchan)))
                    (doubler uchan dchan))))))
doubler)
```



## A quick example: transducer fusion

$\Delta$ CFA can fuse composed transducers into a single loop:

(compose/pull put5 doubler)



## Still to come

- ▶ “Gradient” filtering.
- ▶ Contour GC.
- ▶ More experience with implementation.
- ▶ Context-free grammar or PDA abstractions for  $F$ ?

Questions, Comments, Suggestions?



## Question

What do you mean by “beyond the reach of  $\beta$  reduction?”

## Answer

Certain loop-based optimizations are not possible with  $\beta$  reduction alone.

## Example

```
(letrec ((lp1 ( $\lambda$  (i x)
              (if-zero i x
                (letrec ((lp2 ( $\lambda$  (j f y)
                              (if-zero j
                                (lp1 (- i 1) y)
                                (lp2 (- j 1)
                                    f
                                    [f y])))
                              (lp2 10 [ $\lambda$  (n) (+ n i)] x))))))
          (lp1 10 0))
```

## Question

What did you mean by frame strings “form a group”?

## Answer

- ▶ Elements of group: Equivalence classes under net.
- ▶ Canonical member: The shortest.
- ▶ Identity element:  $\{p : \lfloor p \rfloor = \epsilon\}$ .
- ▶ + operator: Concatenate the cartesian product.
- ▶ Inverse: Invert every member of the class.

# Concrete super- $\beta$ I

$Local\text{-Inlinable}((\kappa', \psi'), pr) \iff$

$\forall (\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \beta, ve, \delta, t) \in \mathcal{V}(pr) :$

if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \beta_b, t_b) = \mathcal{A} \beta \ ve \ t \ f$

then  $\left\{ \begin{array}{l} \psi = \psi' \\ \exists \vec{\gamma} : \left\{ \begin{array}{l} \llbracket [t_b, t] \rrbracket \succ \vec{\gamma} \in \\ free(L_{pr}(\psi')) \subseteq \overline{B(\vec{\gamma})}. \end{array} \right. \end{array} \right.$

# Abstract super- $\beta$ I

$\widehat{Local-Inlinable}((\kappa', \psi'), pr) \iff$

$\forall (\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \widehat{\beta}, \widehat{ve}, \widehat{\delta}, \widehat{t}) \in \widehat{\mathcal{V}}(pr) :$

if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \widehat{\beta}_b, \widehat{t}_b) = \widehat{\mathcal{A}} \widehat{\beta} \widehat{ve} \widehat{t} f$

then  $\left\{ \begin{array}{l} \psi = \psi' \\ \exists \vec{\gamma} : \left\{ \begin{array}{l} \widehat{\delta}(\widehat{t}_b) \approx^{\vec{\gamma}} |\epsilon| \\ free(L_{pr}(\psi')) \subseteq \overline{B(\vec{\gamma})}. \end{array} \right. \end{array} \right.$

## Concrete super- $\beta$ II

*Escaping-Inlinable* $((\kappa', \psi'), pr) \iff$

$\forall (\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \beta, ve, \delta, t) \in \mathcal{V}(pr) :$

if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \beta_b, t_b) = \mathcal{A} \beta \ ve \ t \ f$

then  $\begin{cases} \psi = \psi' \\ \forall v \in \text{free}(L_{pr}(\psi)) : \exists \vec{\gamma} : \begin{cases} \llbracket [\beta(v), t] \rrbracket \succ^{\vec{\gamma}} \llbracket [t_b, t] \rrbracket \\ v \notin B(\vec{\gamma}). \end{cases} \end{cases}$

# Abstract super- $\beta$ II

*Escaping-Inlinable* $((\kappa', \psi'), pr) \iff$

$\forall (\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \widehat{\beta}, \widehat{ve}, \widehat{\delta}, \widehat{t}) \in \widehat{\mathcal{V}}(pr) :$

if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \widehat{\beta}_b, \widehat{t}_b) = \widehat{\mathcal{A}} \widehat{\beta} \widehat{ve} \widehat{t} f$

then  $\begin{cases} \psi = \psi' \\ \forall v \in \text{free}(L_{pr}(\psi)) : \exists \vec{\gamma} : \begin{cases} \widehat{\delta}(\widehat{\beta}(v)) \succeq^{\vec{\gamma}} \widehat{\delta}(\widehat{t}_b) \\ v \notin B(\vec{\gamma}). \end{cases} \end{cases}$

## Concrete super- $\beta$ III

*General-Inlinable* $((\kappa', \psi'), pr) \iff$

$\forall (\llbracket (f \ e^* \ q^*)_{\kappa} \rrbracket, \beta, ve, \delta, t) \in \mathcal{V}(pr) :$

if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \beta_b, t_b) = \mathcal{A} \beta \ ve \ t \ f$

then  $\begin{cases} \psi = \psi' \\ \forall v \in \mathit{free}(L_{pr}(\psi)) : \llbracket [\beta(v), t] \rrbracket = \llbracket [\beta_b(v), t] \rrbracket. \end{cases}$

# Abstract super- $\beta$ III

$\widehat{General-Inlinable}((\kappa', \psi'), pr) \iff$

$\forall ([[f \ e^* \ q^*]_{\kappa}], \widehat{\beta}, \widehat{ve}, \widehat{\delta}, \widehat{t}) \in \widehat{\mathcal{V}}(pr) :$

if  $\kappa = \kappa'$  and  $(L_{pr}(\psi), \widehat{\beta}_b, \widehat{t}_b) = \widehat{\mathcal{A}} \widehat{\beta} \widehat{ve} \widehat{t} f$

then  $\begin{cases} \psi = \psi' \\ \forall v \in \mathit{free}(L_{pr}(\psi)) : \widehat{\delta}(\widehat{\beta}(v)) \succeq^{\emptyset} \widehat{\delta}(\widehat{\beta}_b(v)). \end{cases}$